# Almost periodic solutions of neutral delay functional differential equations on time scales \*

Meng Hu<sup>1</sup><sup>†</sup>, Pingli Xie<sup>2</sup>

<sup>1</sup>School of mathematics and statistics, Anyang Normal University Anyang, Henan 455000, People's Republic of China <sup>2</sup>School of Science, Henan University of Technology Zhengzhou, Henan 450001, People's Republic of China

#### Abstract

In this paper, based on the properties of almost periodic function and exponential dichotomy of linear system on time scales as well as Krasnoselskii's fixed point theorem, some sufficient conditions are established for the existence of almost periodic solutions of delayed neutral functional differential equations on time scales. Finally, an example is presented to illustrate the feasibility and effectiveness of the results.

**Key words:** Neutral differential equation; Almost periodic solution; Exponential dichotomy; Krasnoselskii's fixed point theorem; Time scale.

2010 Mathematics Subject Classification: 34K14; 34K40; 34N05

# 1 Introduction

Neutral differential and difference equations arise in many areas of applied mathematics, such as population dynamics [1], stability theory [2], circuit theory [3], bifurcation analysis [4], dynamical behavior of delayed network systems [5], and so on. Also, qualitative analysis such as periodicity and almost periodicity of neutral differential and difference equations received more recently researchers' special attention due to their applications, see [6-8] and the references therein.

However, in the real world, there are many systems whose developing processes are both continuous and discrete. Hence, using the only differential equation or difference equation can't accurately describe the law of their developments. Therefore, there is a need to establish correspondent dynamic models on new time scales.

The theory of calculus on time scales (see [9] and references cited therein) was initiated by Stefan Hilger in his Ph.D. thesis in 1988 [10] in order to unify continuous and discrete

<sup>\*</sup>This work is supported by the National Natural Sciences Foundation of China (Tianyuan Fund for Mathematics, Grant No. 11126272) and High-Level Personal Foundation of Henan University of Technology (Grant No. 2009BS066).

<sup>&</sup>lt;sup>†</sup>The corresponding author. E-mail address: humeng2001@126.com.

analysis, and it has a tremendous potential for applications and has recently received much attention since his foundational work, one may see [11-15]. Therefore, it is practicable to study that on time scales which can unify the continuous and discrete situations.

Motivated by the above, in the present paper, we focus on the following neutral delay functional differential equations on time scales:

$$x^{\Delta}(t) = A(t)x(t) + Q^{\Delta}(t, x_t) + G(t, x(t), x_t), \ t \in \mathbb{T}.$$
(1.1)

where  $\mathbb{T}$  is an almost periodic time scale, A(t) is a nonsingular  $n \times n$  matrix with continuous real-valued functions as its elements; the functions  $Q : \mathbb{T} \times \mathbb{R}^n \to \mathbb{R}^n$  and  $G : \mathbb{T} \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n$ are continuous with their arguments, respectively;  $x_t \in C(\mathbb{T}, \mathbb{R}^n)$ , and  $x_t(s) = x(t+s)$ , for all  $s \in \mathbb{T}$ .

**Remark 1.1.** The neutral differential and difference equations considered in [6-8] are the special cases of (1.1). To the best knowledge of the authors, there are few papers in literature dealing with the existence of almost periodic solutions of neutral delayed functional differential equations on time scales.

The purpose of this paper is to establish the existence of almost periodic solutions of (1.1) based on the properties of almost periodic function and exponential dichotomy of linear system on time scales as well as Krasnoselskii's fixed point theorem.

In this paper, for each  $\phi = (\phi_1, \phi_2, \cdots, \phi_n)^T \in C(\mathbb{T}, \mathbb{R}^n)$ , the norm of  $\phi$  is defined as  $\|\phi\| = \sup_{t \in \mathbb{T}} |\phi(t)|_0$ , where  $|\phi(t)|_0 = \sum_{i=1}^n |\phi_i(t)|$ ; and when it comes to that  $\phi$  is continuous, delta derivative, delta integrable, and so forth, we mean that each element  $\phi_i$  is continuous, delta derivative, delta integrable, and so forth.

# 2 Preliminaries

Let  $\mathbb{T}$  be a nonempty closed subset (time scale) of  $\mathbb{R}$ . The forward and backward jump operators  $\sigma, \rho : \mathbb{T} \to \mathbb{T}$  and the graininess  $\mu : \mathbb{T} \to \mathbb{R}^+$  are defined, respectively, by

$$\sigma(t) = \inf\{s \in \mathbb{T} : s > t\}, \ \rho(t) = \sup\{s \in \mathbb{T} : s < t\}, \ \mu(t) = \sigma(t) - t.$$

A point  $t \in \mathbb{T}$  is called left-dense if  $t > \inf \mathbb{T}$  and  $\rho(t) = t$ , left-scattered if  $\rho(t) < t$ , right-dense if  $t < \sup \mathbb{T}$  and  $\sigma(t) = t$ , and right-scattered if  $\sigma(t) > t$ . If  $\mathbb{T}$  has a left-scattered maximum m, then  $\mathbb{T}^k = \mathbb{T} \setminus \{m\}$ ; otherwise  $\mathbb{T}^k = \mathbb{T}$ . If  $\mathbb{T}$  has a right-scattered minimum m, then  $\mathbb{T}_k = \mathbb{T} \setminus \{m\}$ ; otherwise  $\mathbb{T}_k = \mathbb{T}$ .

A function  $f : \mathbb{T} \to \mathbb{R}$  is right-dense continuous provided it is continuous at right-dense point in  $\mathbb{T}$  and its left-side limits exist at left-dense points in  $\mathbb{T}$ . If f is continuous at each right-dense point and each left-dense point, then f is said to be a continuous function on  $\mathbb{T}$ .

The basic theories of calculus on time scales, one can see [9].

A function  $p : \mathbb{T} \to \mathbb{R}$  is called regressive provided  $1 + \mu(t)p(t) \neq 0$  for all  $t \in \mathbb{T}^k$ . The set of all regressive and rd-continuous functions  $p : \mathbb{T} \to \mathbb{R}$  will be denoted by  $\mathcal{R} = \mathcal{R}(\mathbb{T}, \mathbb{R})$ .

If r is a regressive function, then the generalized exponential function  $e_r$  is defined by

$$e_r(t,s) = \exp\left\{\int_s^t \xi_{\mu(\tau)}(r(\tau))\Delta\tau\right\}$$

for all  $s, t \in \mathbb{T}$ , with the cylinder transformation

$$\xi_h(z) = \begin{cases} \frac{\log(1+hz)}{h}, & \text{if } h \neq 0, \\ z, & \text{if } h = 0. \end{cases}$$

Let  $p, q: \mathbb{T} \to \mathbb{R}$  be two regressive functions, define

$$p \oplus q = p + q + \mu p q, \quad \ominus p = -\frac{p}{1 + \mu p}, \quad p \ominus q = p \oplus (\ominus q).$$

**Lemma 2.1.** (see [9]) Assume that  $p, q : \mathbb{T} \to \mathbb{R}$  be two regressive functions, then (i)  $e_0(t,s) \equiv 1$  and  $e_p(t,t) \equiv 1$ ; (ii)  $e_p(\sigma(t),s) = (1 + \mu(t)p(t))e_p(t,s)$ ; (iii)  $e_p(t,s) = \frac{1}{e_p(s,t)} = e_{\ominus p}(s,t)$ ;

(iii)  $e_p(t,s) = e_p(s,t)$  (iv)  $e_p(t,s) = e_p(t,r);$ 

 $(v) \ (e_{\ominus p}(t,s))^{\Delta} = (\ominus p)(t)e_{\ominus p}(t,s).$ 

**Lemma 2.2.** (see [9]) If  $p \in \mathcal{R}$  be an  $n \times n$ -matrix-valued function on  $\mathbb{T}$  and  $a, b, c \in \mathbb{T}$ , then

$$[e_p(c,\cdot)]^{\Delta} = -p[e_p(c,\cdot)]^{\sigma} \text{ and } \int_a^b p(t)e_p(c,\sigma(t))\Delta t = e_p(c,a) - e_p(c,b).$$

The definitions of almost periodic function and uniformly almost periodic function on time scales can be found in [16,17].

In what follows, we need the following notation. For every real sequence  $\alpha = (\alpha_n)$  and a continuous function  $f: \mathbb{T} \to \mathbb{R}^n$ , define  $T_{\alpha}f = \lim_{n \to \infty} f(t + \alpha_n)$  if  $\lim_{n \to \infty} f(t + \alpha_n)$  exists.

**Lemma 2.3.** A function  $f : \mathbb{T} \to \mathbb{R}^n$  is almost periodic if and only if f is continuous and for each  $\alpha = (\alpha_n)$ , there exists a subsequence  $\alpha'$  of  $(\alpha_n)$  such that  $\mathbb{T}_{\alpha'}f = g$  uniformly on  $\mathbb{T}$ .

**Lemma 2.4.** Let  $f : \mathbb{T} \to \mathbb{R}^n$  is an almost periodic function, then f(t) is bounded and uniformly continuous on  $\mathbb{T}$ .

The proofs of Lemma 2.3 and Lemma 2.4 are similar to the Theorem 3.13 in [18] and the Theorem 1.1 in [19], respectively. Hence, we omit it.

**Lemma 2.5.** If  $f : \mathbb{T} \times \mathbb{R}^n \to \mathbb{R}^n$  is an almost periodic function in t uniformly for  $x \in \mathbb{R}^n$ , then f(t, x) is bounded on  $\mathbb{T} \times D$ , where D is any compact subset of  $\mathbb{R}^n$ .

*Proof.* For given  $\varepsilon \leq 1$  and a compact subset  $D \subset \mathbb{R}^n$ , there exists a constant l, such that in any interval of length  $l(\varepsilon, D)$ , f(t, x) is uniformly continuous on  $[0, l(\varepsilon, D)] \times D$ . Therefore, there exists a number M > 0, such that

 $|f(t,x)|_0 < M$ , for  $(t,x) \in [0, l(\varepsilon, D)] \times D$ .

For any  $t \in \mathbb{T}$ , we can take  $\tau \in E\{\varepsilon, f\} \cap [-t, -t + l(\varepsilon, D)]$ , then we have  $t + \tau \in [0, l(\varepsilon, D)]$ . Hence, we can obtain

$$|f(t+\tau, x)|_0 < M, \forall x \in D$$

and

$$|f(t+\tau, x) - f(t, x)|_0 < \varepsilon \le 1, \forall (t, x) \in \mathbb{T} \times D.$$

Hence, for any  $(t, x) \in \mathbb{T} \times D$ , we have

 $|f(t,x)|_0 \le |f(t+\tau,x)|_0 + |f(t+\tau,x) - f(t,x)|_0 < M+1.$ 

That is, f(t, x) is bounded on  $\mathbb{T} \times D$ . The proof is completed.

**Lemma 2.6.** If  $f : \mathbb{T} \times \mathbb{R}^n \to \mathbb{R}^n$  is an almost periodic function in t uniformly for  $x \in \mathbb{R}^n$ ,  $\phi(t)$  is also an almost periodic function and  $\phi(t) \subset S$  for all  $t \in \mathbb{T}$ , S is a compact subset of  $\mathbb{R}^n$ , then  $f(t, \phi(t))$  is almost periodic.

Proof. For any real sequence  $\alpha'$ , we can find a subsequence  $\alpha \subset \alpha'$ . Assume that  $\varphi(t)$  is an almost periodic function, g(t,x) is an almost periodic function in t uniformly for  $x \in \mathbb{R}^n$ , we make that  $T_{\alpha}f(t,x) = g(t,x)$  uniformly on  $\mathbb{T}$  and  $T_{\alpha}\phi(t) = \varphi(t)$  also uniformly on  $\mathbb{T}$ . Hence, g(t,x) is uniformly continuous on  $\mathbb{T} \times S$ . For any  $\varepsilon > 0$ , there exists a positive number  $\delta(\frac{\varepsilon}{2}) > 0$ ,  $\forall x_1, x_2 \in S$ , such that  $|x_1 - x_2|_0 < \delta(\frac{\varepsilon}{2})$  implies  $|g(t,x_1) - g(t,x_2)|_0 < \frac{\varepsilon}{2}$ , for any  $t \in \mathbb{T}$ , and there exists a positive integer  $N_0(\varepsilon) > 0$ , when  $n \ge N_0(\varepsilon)$ , we have

$$|f(t + \alpha_n, x) - g(t, x)|_0 < \frac{\varepsilon}{2}, \ \forall (t, x) \in \mathbb{T} \times S$$

and

$$|\phi(t+\alpha_n)-\varphi(t)|_0 < \delta(\frac{\varepsilon}{2}), \ \forall t \in \mathbb{T}$$

Moreover,  $\phi(t + \alpha_n) \subset S, \varphi(t) \subset S$  for all  $t \in \mathbb{T}$ . Then, when  $n \geq N_0(\varepsilon)$ , it is easy to see that

$$\begin{aligned} &|f(t+\alpha_n,\phi(t+\alpha_n)) - g(t,\varphi(t))|_0\\ &\leq |f(t+\alpha_n,\phi(t+\alpha_n)) - g(t,\phi(t+\alpha_n))|_0 + |g(t,\phi(t+\alpha_n)) - g(t,\varphi(t))|_0\\ &< \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon. \end{aligned}$$

Hence,  $T_{\alpha}f(t,\phi(t)) = g(t,\varphi(t))$  uniformly on  $\mathbb{T}$ . So  $f(t,\phi(t))$  is an almost periodic function. The proof is completed.

**Lemma 2.7.** If  $u : \mathbb{T} \to \mathbb{R}^n$  is an almost periodic function, then  $u_t$  is almost periodic.

*Proof.* It is clear that  $u_t$  is continuous for  $t \in \mathbb{T}$ . For any sequence  $\alpha' = (\alpha'_n)$ . Since u(t) is an almost periodic function, then there exists a subsequence  $\alpha = (\alpha_n)$  of  $(\alpha'_n)$ , such that

$$T_{\alpha}u(t) = \overline{u}(t) \tag{2.1}$$

uniformly for  $t \in \mathbb{T}$ . On the other hand, since u(t) is an almost periodic function, it is uniformly continuous on  $\mathbb{T}$ . For any  $\varepsilon > 0$ , there exists a positive number  $\delta(\varepsilon)$ , such that  $|t_1 - t_2| < \delta$  implies  $|u(t_1) - u(t_2)|_0 < \varepsilon$ . From (2.1), there exists a positive integer N, such that

 $|u(t+\alpha_n)-\overline{u}(t)|_0 < \varepsilon, \ t \in \mathbb{T},$ 

when n > N, we have

$$(u_t)_{\alpha_n} - \overline{u}_t|_0 = |u(t + \alpha_n + \theta) - \overline{u}(t + \theta)|_0 < \varepsilon.$$

Hence  $u(t + \alpha_n)$  converges to  $\overline{u}_t$  uniformly on  $\mathbb{T}$ . So  $u_t$  is almost periodic. The proof is completed.

**Definition 2.1.** (see [16]) Let  $x \in \mathbb{R}^n$  and A(t) be an  $n \times n$  rd-continuous matrix on  $\mathbb{T}$ , the linear system

$$x^{\Delta}(t) = A(t)x(t) \tag{2.2}$$

is said to admit an exponential dichotomy on  $\mathbb{T}$ , if there exist positive constants  $\alpha > 0, k \ge 1$ , projection P and the fundamental solution matrix X(t) of (2.2) satisfying

$$\|X(t)PX^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t \in \mathbb{T}, t \ge \sigma(s),$$
(2.3)

$$\|X(t)(I-P)X^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(\sigma(s),t) \quad s,t\in\mathbb{T},t\le\sigma(s),$$
(2.4)

where  $\|\cdot\|$  is a matrix norm on  $\mathbb{T}$ .

**Remark 2.1.** It is clear that when A(t) = diag(1, -1), (2.2) admits exponential dichotomy. More generally, in the case  $A(t) \equiv A$ , a constant matrix, (2.2) admits exponential dichotomy if and only if the eigenvalues of A have a nonzero real part.

**Lemma 2.8.** Suppose (2.2) admits exponential dichotomy, that is, there exist constants  $\alpha > 0, k \geq 1$ , such that (2.3), (2.4) hold. If  $A(t+t_k)$  converges to  $\overline{A}(t)$  uniformly on any compact subset of  $\mathbb{T}$ , then  $\{X(t+t_k)PX^{-1}(\sigma(s)+t_k)\}$  and  $\{X(t+t_k)(I-P)X^{-1}(\sigma(s)+t_k)\}$  converges to  $\{\overline{X}(t)\overline{P}\,\overline{X}^{-1}(\sigma(s))\}$  and  $\{\overline{X}(t)(I-\overline{P})\overline{X}^{-1}(\sigma(s))\}$  uniformly on any compact subset  $\mathbb{T} \times \mathbb{T}$ , respectively. Furthermore, the following inequalities hold:

$$\begin{aligned} \|\overline{X}(t)\overline{P}\,\overline{X}^{-1}(\sigma(s))\| &\leq k e_{\ominus\alpha}(t,\sigma(s)) \quad s,t \in \mathbb{T}, t \geq \sigma(s), \\ \|\overline{X}(t)(I-\overline{P})\overline{X}^{-1}(\sigma(s))\| &\leq k e_{\ominus\alpha}(\sigma(s),t) \quad s,t \in \mathbb{T}, t \leq \sigma(s), \end{aligned}$$

where  $\overline{X}$  is the fundamental matrix solution of the following equation

$$x^{\Delta}(t) = \overline{A}(t)x. \tag{2.5}$$

*Proof.* we first prove that  $\{X(t_k)PX^{-1}(t_k)\}$  is convergent. From (2.3), we see that

$$||X(t_k)PX^{-1}(t_k)|| \le k.$$

Suppose  $\{X(t_k)PX^{-1}(t_k)\}$  is not convergent. Then we can find two subsequence:

$$\{X(t_{k_m})PX^{-1}(t_{k_m})\}, \{X(t_{k'_m})PX^{-1}(t_{k'_m})\},\$$

such that

$$\lim_{m \to \infty} X(t_{k_m}) P X^{-1}(t_{k_m}) = \overline{P}, \quad \lim_{m \to \infty} X(t_{k'_m}) P X^{-1}(t_{k'_m}) = \underline{P},$$

and  $\overline{P} \neq \underline{P}$ .

Then from (2.3) we have

$$\|X(t+t_{k_m})PX^{-1}(\sigma(s)+t_{k_m})\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s),$$
(2.6)

and

$$\|X(t+t_{k'_m})PX^{-1}(\sigma(s)+t_{k'_m})\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s).$$

$$(2.7)$$

Assume that  $X_{k_m}(t), X_{k'_m}(t)$  are the fundamental matrix solutions of systems

$$x^{\Delta}(t) = A(t + t_{k_m})x, \ x^{\Delta}(t) = A(t + t_{k'_m})x$$

respectively, then  $X(t + t_{k_m}) = X_{k_m}(t)X(t_{k_m})$ ,  $X(t + t_{k'_m}) = X_{k'_m}(t)X(t_{k'_m})$ . Since  $\{A(t + t_k)\}$ converges to  $\overline{A}(t)$  uniformly on any compact subset of  $\mathbb{T}$ , then  $\{A(t + t_k)x\}$  converges to  $\overline{A}(t)x$ uniformly on any compact subset of  $\mathbb{T} \times \mathbb{R}^n$ . It follows that  $\{A(t + t_{k_m})x\}$  and  $\{A(t + t_{k'_m})x\}$ converge to  $\overline{A}(t)x$  uniformly on any compact subset of  $\mathbb{T} \times \mathbb{R}^n$ . So  $X_{k_m}(t), X_{k'_m}(t)$  converge to  $\overline{X}(t)$  uniformly on any compact set of  $\mathbb{T}$ . Furthermore, it follows from (2.6), (2.7) that

$$\|X_{k_m}(t)X(t_{k_m})PX^{-1}(t_{k_m})X_{k_m}^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s)$$

and

$$\|X_{k'_m}(t)X(t_{k'_m})PX^{-1}(t_{k'_m})X^{-1}_{k'_m}(\sigma(s))\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s).$$

Let  $m \to \infty$ , we have

$$\|\overline{X}(t)\overline{P}\,\overline{X}^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s)$$
(2.8)

and

$$\|\overline{X}(t)\underline{P}\,\overline{X}^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s).$$
(2.9)

Similarly, we can obtain

$$\|\overline{X}(t)(I-\overline{P})\overline{X}^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(\sigma(s),t) \quad s,t\in\mathbb{T},t\le\sigma(s)$$
(2.10)

and

$$\|\overline{X}(t)(I-\underline{P})\overline{X}^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(\sigma(s),t) \quad s,t\in\mathbb{T},t\le\sigma(s).$$
(2.11)

From (2.8)-(2.11), we see that (2.5) admits exponential dichotomy; both  $\overline{P}$  and  $\underline{P}$  are its projections. So  $\overline{P} = \underline{P}$ , which is a contradiction. Hence,  $\{X(t_k)PX^{-1}(t_k)\}$  is convergent.

Let  $\{X(t_k)PX^{-1}(t_k)\} \to \overline{P}$  as  $k \to \infty$ . Now assume that  $X_k(t)$  is the fundamental matrix solution of the system  $x^{\Delta}(t) = A(t+t_k)x$ , then  $X_k(t)$  converges to  $\overline{X}(t)$  uniformly on any compact set of  $\mathbb{T}$ . It is easy to see that  $\{X_k^{-1}(\sigma(s))\}$  converges to  $\overline{X}^{-1}(\sigma(s))$  uniformly on any compact subset of  $\mathbb{T}$ . So  $X(t+t_k)PX^{-1}(\sigma(s)+t_k)$  and  $\{X(t+t_k)(I-P)X^{-1}(\sigma(s)+t_k)\}$ converges to  $\overline{X}(t)\overline{P}\overline{X}^{-1}(\sigma(s))$  and  $\overline{X}(t)(I-\overline{P})\overline{X}^{-1}(\sigma(s))$  uniformly on any compact subset  $\mathbb{T} \times \mathbb{T}$ , respectively. Furthermore, from (2.6) and (2.7) we have

$$||X(t+t_k)PX^{-1}(\sigma(s)+t_k)|| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s)$$

and

$$||X(t+t_k)(I-P)X^{-1}(\sigma(s)+t_k)|| \le ke_{\ominus\alpha}(\sigma(s),t) \quad s,t\in\mathbb{T},t\le\sigma(s).$$

That is,

$$|X_k(t)X(t_k)PX^{-1}(t_k)X_k^{-1}(\sigma(s))|| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t \in \mathbb{T}, t \ge \sigma(s)$$

and

$$|X_k(t)X(t_k)(I-P)X^{-1}(t_k)X_k^{-1}(\sigma(s))|| \le ke_{\ominus\alpha}(\sigma(s),t) \quad s,t\in\mathbb{T}, t\le\sigma(s).$$

Let  $k \to \infty$ , we obtain

$$\|\overline{X}(t)\overline{P}\,\overline{X}^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(t,\sigma(s)) \quad s,t\in\mathbb{T},t\ge\sigma(s)$$

and

$$\|\overline{X}(t)(I-\overline{P})\overline{X}^{-1}(\sigma(s))\| \le ke_{\ominus\alpha}(\sigma(s),t) \quad s,t\in\mathbb{T},t\le\sigma(s).$$

The proof is completed.

**Lemma 2.9.** (see [20]) Let M be a closed convex nonempty subset of a Banach space  $(B, \|\cdot\|)$ . Suppose that B and C map M into B, such that (1)  $x, y \in M$ , implies  $Bx + Cy \in M$ , (2) C is continuous and C(M) is contained in a compact set, (3) B is a contraction mapping. Then there exists  $z \in M$  with z = Bz + Cz.

### 3 Main results

Let  $AP(\mathbb{T})$  be the set of all almost periodic functions on almost times scales  $\mathbb{T}$ , then  $(AP(\mathbb{T}), \|\cdot\|)$  is a Banach space with the supremum norm given by  $\|\psi\| = \sup_{t \in \mathbb{T}} |\psi(t)|_0$ , where

 $|\psi(t)|_0 = \sum_{i=1}^n |\psi_i(t)|.$ 

Hereafter, we make the following assumptions:

 $(H_1)$  There exist positive numbers  $L_Q, L_G$  such that

$$|Q(t,\phi_t) - Q(t,\varphi_t)|_0 \le L_Q |\phi_t - \varphi_t|_0 \tag{3.1}$$

for all  $t \in \mathbb{T}$ ,  $\phi_t, \varphi_t \in AP(\mathbb{T})$ , and

$$|G(t, u, \phi_t) - G(t, v, \varphi_t)|_0 \le L_G(|u - v|_0 + |\phi_t - \varphi_t|_0)$$
(3.2)

for all  $t \in \mathbb{T}$ ,  $(u, \phi_t), (v, \varphi_t) \in \mathbb{R}^n \times AP(\mathbb{T})$ .

- (H<sub>2</sub>) A(t) is an almost periodic function,  $Q(t, u_t)$  is an almost periodic function in t uniformly for  $u_t \in AP(\mathbb{T})$ , and  $G(t, u, u_t)$  is also an almost periodic function in t uniformly for  $u, u_t \in \mathbb{R}^n \times AP(\mathbb{T})$ .
- (H<sub>3</sub>) System (2.2) admits exponential dichotomy, that is, there exist constants  $\alpha > 0, k \ge 1$ , such that (2.3) and (2.4) hold.

Define a mapping  $\Phi$  by

$$(\Phi u)(t) = Q(t, u_t) + \int_{-\infty}^{t} X(t) P X^{-1}(\sigma(s)) G(s, u(s), u_s) \Delta s - \int_{t}^{+\infty} X(t) (I - P) X^{-1}(\sigma(s)) G(s, u(s), u_s) \Delta s.$$
(3.3)

#### **Lemma 3.1.** If u is an almost periodic function, then $\Phi u$ is an almost periodic function.

*Proof.* For u(t) is an almost periodic function, from  $(H_2)$ , Lemma 2.4 to Lemma 2.7, then  $Q(t, u_t), G(t, u(t), u_t)$  are all almost periodic functions, so they are uniformly bounded on  $\mathbb{T}$ . Let  $M_1, M_2$  be positive numbers such that

$$||Q(\cdot, u_{\cdot})|| \le M_1, ||G(\cdot, u(\cdot), u_{\cdot})|| \le M_2.$$

Now, we prove that  $(\Phi u)(t)$  is an almost periodic function. First, it is clear that  $(\Phi u)(t)$  is continuous on  $\mathbb{T}$ . For any sequence  $\alpha = (\alpha_n)$ , since  $Q(t, u_t), G(t, u(t), u_t)$  are almost periodic functions, combining with Lemma 2.3 and Lemma 2.8, we can find a common subsequence of  $(\alpha_n)$ , we still denote it as  $(\alpha_n)$ , such that

$$T_{\alpha}Q(t, u_t) = Q_1(t), \quad T_{\alpha}G(t, u(t), u_t) = G_1(t)$$
(3.4)

uniformly for  $t \in \mathbb{T}$  and

$$\lim_{k \to \infty} X(t + \alpha_k) P X^{-1}(\sigma(s) + \alpha_k) = \overline{X}(t) \overline{P} \, \overline{X}^{-1}(\sigma(s)), t \ge \sigma(s)$$
(3.5)

$$\lim_{k \to \infty} X(t + \alpha_k)(I - P)X^{-1}(\sigma(s) + \alpha_k) = \overline{X}(t)(I - \overline{P})\overline{X}^{-1}(\sigma(s)), t \le \sigma(s).$$
(3.6)

Then

$$(\Phi u)(t + \alpha_k) = Q(t + \alpha_k, u_{t+\alpha_k}) + \int_{-\infty}^{t+\alpha_k} X(t + \alpha_k) P X^{-1}(\sigma(s)) G(s, u(s), u_s) \Delta s$$
  

$$- \int_{t+\alpha_k}^{+\infty} X(t + \alpha_k) (I - P) X^{-1}(\sigma(s)) G(s, u(s), u_s) \Delta s$$
  

$$= Q(t + \alpha_k, u_{t+\alpha_k}) + \int_{-\infty}^{t} X(t + \alpha_k) P X^{-1}(\sigma(s) + \alpha_k)$$
  

$$\times G(s + \alpha_k, u(s + \alpha_k), u_{s+\alpha_k}) \Delta s$$
  

$$- \int_{t}^{+\infty} X(t + \alpha_k) (I - P) X^{-1}(\sigma(s) + \alpha_k)$$
  

$$\times G(s + \alpha_k, u(s + \alpha_k), u_{s+\alpha_k}) \Delta s.$$

From (3.4)-(3.6) and Lebesgue's control convergence theorem, we see that  $(\Phi u)(t + \alpha_k)$  converges to

$$Q_1(t) + \int_{-\infty}^t \overline{X}(t)\overline{P}\,\overline{X}^{-1}(\sigma(s))G_1(s)\Delta s - \int_t^{+\infty} \overline{X}(t)(I-\overline{P})\overline{X}^{-1}(\sigma(s))G_1(s)\Delta s$$

uniformly for  $t \in \mathbb{T}$ . So,  $(\Phi u)(t)$  is an almost periodic function. The proof is completed.

In order to apply Krasnoselskii's theorm, we need to construct two mappings, one is a contraction and the other is compact. Let

$$(\Phi u)(t)(Bu)(t) + (Cu)(t),$$
where  $B, C : AP(\mathbb{T}) \to AP(\mathbb{T})$  are given by
$$(Bu)(t) = Q(t, u_t),$$

$$(Cu)(t) = \int_{-\infty}^{t} X(t)PX^{-1}(\sigma(s))G(s, u(s), u_s)\Delta s$$

$$-\int_{t}^{+\infty} X(t)(I-P)X^{-1}(\sigma(s))G(s, u(s), u_s)\Delta s.$$
(3.8)

**Lemma 3.2.** (see [7]) The operator B is a contraction provided  $L_Q < 1$ .

**Lemma 3.3.** The operator C is continuous and the image C(M) is contained in a compact set, where  $M = \{u \in AP(\mathbb{T}) : ||u|| \leq R\}$ , R is a fixed constant.

*Proof.* First, by (3.8), we have

$$\begin{aligned} \|(Cu)(\cdot)\| &\leq \int_{-\infty}^{t} \|X(t)PX^{-1}(\sigma(s))\| \|G(\cdot, u(\cdot), u_{\cdot})\|\Delta s \\ &+ \int_{t}^{+\infty} \|X(t)(I-P)X^{-1}(\sigma(s))\| \|G(\cdot, u(\cdot), u_{\cdot})\|\Delta s \\ &\leq \|G(\cdot, u(\cdot), u_{\cdot})\| \left(\int_{-\infty}^{t} \|X(t)PX^{-1}(\sigma(s))\|\Delta s \\ &+ \int_{t}^{+\infty} \|X(t)(I-P)X^{-1}(\sigma(s))\|\Delta s\right) \\ &\leq \|G(\cdot, u(\cdot), u_{\cdot})\| \left(\int_{-\infty}^{t} ke_{\ominus\alpha}(t, \sigma(s))\Delta s + \int_{t}^{+\infty} ke_{\ominus\alpha}(\sigma(s), t)\Delta s\right). \end{aligned}$$

By Lemma 2.2, we can get

$$\int_{-\infty}^{t} k e_{\ominus \alpha}(t, \sigma(s)) \Delta s + \int_{t}^{+\infty} k e_{\ominus \alpha}(\sigma(s), t) \Delta s \leq k(\frac{1}{\alpha} - \frac{1}{\ominus \alpha}).$$

Therefore,

$$\|(Cu)(\cdot)\| \le k(\frac{1}{\alpha} - \frac{1}{\ominus \alpha}) \|G(\cdot, u(\cdot), u_{\cdot})\|.$$

$$(3.9)$$

Now, we show that C is continuous. In fact, let  $u, v \in AP(\mathbb{T})$ , for any  $\varepsilon > 0$ , take  $\delta = \varepsilon/[2kL_G(\frac{1}{\alpha} - \frac{1}{\ominus \alpha})]$ , whenever  $||u - v|| < \delta$ , we have

$$\begin{split} \|(Cu)(\cdot) - (Cv)(\cdot)\| \\ &\leq \int_{-\infty}^{t} \|X(t)PX^{-1}(\sigma(s))\| \|G(\cdot, u(\cdot), u_{\cdot}) - G(\cdot, v(\cdot), v_{\cdot})\|\Delta s \\ &+ \int_{t}^{+\infty} \|X(t)(I - P)X^{-1}(\sigma(s))\| \|G(\cdot, u(\cdot), u_{\cdot})) - G(\cdot, v(\cdot), v_{\cdot})\|\Delta s \\ &\leq \int_{-\infty}^{t} ke_{\ominus\alpha}(t, \sigma(s))L_{G}(\|u(\cdot) - v(\cdot)\| + \|u_{\cdot} - v_{\cdot}\|)\Delta s \\ &+ \int_{t}^{+\infty} ke_{\ominus\alpha}(\sigma(s), t)L_{G}(\|u(\cdot) - v(\cdot)\| + \|u_{\cdot} - v_{\cdot}\|) \\ &\leq 2L_{G}\|u - v\|(\int_{-\infty}^{t} ke_{\ominus\alpha}(t, \sigma(s))\Delta s + \int_{t}^{+\infty} ke_{\ominus\alpha}(\sigma(s), t)\Delta s) \\ &\leq 2kL_{G}(\frac{1}{\alpha} - \frac{1}{\ominus\alpha})\|u - v\| \\ &< \varepsilon. \end{split}$$

This proves that C is continuous.

For  $M = \{u \in AP(\mathbb{T}) : ||u|| \leq R\}$ . Now, we show that the image of C(M) is contained in a compact set. In fact, let  $u_n$  be a sequence in M. In view of (3.2), we have

$$\begin{aligned} \|G(\cdot, u(\cdot), u_{\cdot})\| &\leq \|G(\cdot, u(\cdot), u_{\cdot}) - G(\cdot, 0, 0)\| + \|G(\cdot, 0, 0)\| \\ &\leq L_G(\|u\| + \|u_{\cdot}\|) + a \\ &\leq 2L_G R + a, \end{aligned}$$
(3.10)

where  $a = ||G(\cdot, 0, 0)||$ . From (3.9) and (3.10), we have

$$\|Cu_n(\cdot)\| \le k(\frac{1}{\alpha} - \frac{1}{\ominus \alpha})(2L_GR + a) := L.$$
(3.11)

Next, we calculate  $(Cu_n)^{\Delta}(t)$  and show that it is uniformly bounded. By a direct calculate, we have

$$(Cu_n)^{\Delta}(t) = A(t)(Cu_n)(t) + X(t)PX^{-1}(\sigma(s))G(t, u_n(t), (u_n)_t) -X(t)(I-P)X^{-1}(\sigma(s))G(t, u_n(t), (u_n)_t).$$
(3.12)

For A(t) is an almost periodic function, then A(t) is bounded. So, there exists a positive constant  $A_0$ , such that  $||A|| \leq A_0$ . Together with (3.10), (3.11) and (3.12) implies

$$\begin{aligned} \|(Cu_n)^{\Delta}(\cdot)\| &\leq A_0L + (ke_{\ominus\alpha}(t,\sigma(s)) + ke_{\ominus\alpha}(\sigma(s),t)) \|G(\cdot,u_n(\cdot),(u_n))\| \\ &\leq A_0L + (k+k)(2RL_G+a) \\ &\leq A_0L + 2k(2RL_G+a). \end{aligned}$$

Thus the sequence  $(Cu_n)$  is uniformly bounded and equi-continuous. Hence, by the Arzela-Ascoli theorem, C(M) is compact. The proof is completed.

**Theorem 3.1.** Assume that  $(H_1) - (H_3)$  hold. Let  $a = ||G(\cdot, 0, 0)||, b = ||Q(\cdot, 0)||$ . Let  $R_0$  be a positive constant satisfies

$$L_Q R_0 + b + k(\frac{1}{\alpha} - \frac{1}{\ominus \alpha})(2L_G R_0 + a) \le R_0.$$
 (3.13)

Then (1.1) has an almost periodic solution in  $M = \{u \in AP(\mathbb{T}) : ||u|| \le R_0\}.$ 

*Proof.* Define  $M = \{u \in AP(\mathbb{T}) : ||u|| \leq R_0\}$ . By Lemma 3.3, the mapping C defined by (3.8) is continuous and CM is contained in a compact set. By lemma 3.2, the mapping B defined by (3.7) is a contraction and it is clear that  $B : AP(\mathbb{T}) \to AP(\mathbb{T})$ .

Next, we show that if  $u, v \in M$ , we have  $||Bu + Cv|| \leq R_0$ . In fact, let  $u, v \in M$  with  $||u||, ||v|| \leq R_0$ . Then

$$\begin{aligned} |(Bu)(\cdot) + (Cv)(\cdot)|| &\leq \|Q(\cdot, u_{\cdot}) - Q(\cdot, 0)\| + \|Q(\cdot, 0)\| \\ &+ \int_{-\infty}^{t} \|X(t)PX^{-1}(\sigma(s))\| \cdot \|G(\cdot, v(\cdot), v_{\cdot})\|\Delta s \\ &+ \int_{t}^{+\infty} \|X(t)(I - P)X^{-1}(\sigma(s))\| \cdot \|G(\cdot, v(\cdot), v_{\cdot})\|\Delta s \\ &\leq L_{Q}\|u\| + b + k(\frac{1}{\alpha} - \frac{1}{\ominus\alpha})(2L_{G}R + a) \\ &\leq L_{Q}R_{0} + b + k(\frac{1}{\alpha} - \frac{1}{\ominus\alpha})(2L_{G}R_{0} + a) \\ &\leq R_{0}. \end{aligned}$$

Thus  $Bu + Cv \in M$ . Hence all the conditions of Krasnoselskii's theorem are satisfied. Hence there exists a fixed point  $z \in M$ , such that z=Bz+Cz. By Lemma 2.9, (1.1) has an almost periodic solution. The proof is completed.

**Theorem 3.2.** Assume that  $(H_1) - (H_3)$  hold. If

$$L_Q + 2kL_G(\frac{1}{\alpha} - \frac{1}{\ominus \alpha}) < 1, \tag{3.14}$$

then (1.1) has a unique almost periodic solution.

*Proof.* Let the mapping  $\Phi$  be given by (3.3). For  $u, v \in AP(\mathbb{T})$ , in view of (3.3), we have

$$\begin{aligned} &\|(\Phi u)(\cdot) - (\Phi v)(\cdot)\| \\ &\leq \|Q(\cdot, u.) - Q(\cdot, v.)\| \\ &+ \int_{-\infty}^{t} \|X(t)PX^{-1}(\sigma(s))\| \|G(\cdot, u(\cdot), u.) - G(\cdot, v(\cdot), v.)\| \Delta s \\ &+ \int_{t}^{-\infty} \|X(t)(I - P)X^{-1}(\sigma(s))\| \|G(\cdot, u(\cdot), u.) - G(\cdot, v(\cdot), v.)\| \Delta s \\ &\leq L_{Q} \|u - v\| + L_{G} (\|u - v\| + \|u. - v.\|) \cdot (\int_{-\infty}^{t} ke_{\ominus \alpha}(t, \sigma(s)) \Delta s \\ &+ \int_{t}^{+\infty} ke_{\ominus \alpha}(\sigma(s), t) \Delta s) \\ &\leq L_{Q} \|u - v\| + 2L_{G} \|u - v\| k (\frac{1}{\alpha} - \frac{1}{\ominus \alpha}) \\ &= (L_{Q} + 2kL_{G} (\frac{1}{\alpha} - \frac{1}{\ominus \alpha})) \|u - v\|. \end{aligned}$$

This completes the proof by invoking the contraction mapping principle.

**Remark 3.1.** If the conditions of the main result of [7] hold, then (2.2) admits exponential dichotomy with projection P = I, hence system (1.1) has an almost periodic solution. So our main result greatly improves the main result of [7].

### 4 An example

For small positive  $\varepsilon_1$  and  $\varepsilon_2$ , we consider the perturbed Van Der Pol equation

$$x^{\Delta\Delta} + (\varepsilon_2 x^2 - 1)x^{\Delta} + x - \varepsilon_1 (\sin t \, x_t^2)^{\Delta} - \varepsilon_2 \cos t = 0, \tag{4.1}$$

where  $x_t$  is defined by  $x_t(\theta) = x(t+\theta)$  for  $t, \theta \in \mathbb{T}$  is nonnegative, continuous and almost periodic function. Using the transformation  $x_1^{\Delta} = x_2$ , we can transform the above equation to

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}^{\Delta} = \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ \varepsilon_1 \sin tx_{1t}^2 \end{pmatrix}^{\Delta} + \begin{pmatrix} 0 \\ \varepsilon_2 \cos t - \varepsilon_2 x_2 x_1^2 \end{pmatrix},$$
  
that is,  $A = \begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix}, Q(t, x_t) = \begin{pmatrix} 0 \\ \varepsilon_1 \sin tx_{1t}^2 \end{pmatrix}, G(t, x(t), x_t) = \begin{pmatrix} 0 \\ \varepsilon_2 \cos t - \varepsilon_2 x_2 x_1^2 \end{pmatrix}.$ 

Since the real part of the eigenvalues of A is nonzero, by Remark 2.1, we see that  $x^{\Delta}(t) = A(t)x(t)$  admits exponential dichotomy. Let  $\phi(t) = (\phi_1(t), \phi_2(t)), \varphi(t) = (\varphi_1(t), \varphi_2(t))$ . Define  $M = \{u \in AP(\mathbb{T}) : ||u|| \le R_0\}$ , where  $R_0$  is a positive constant.

Then for  $\phi, \varphi \in M$ , we have

$$\|Q(\cdot,\phi) - Q(\cdot,\varphi)\| \le 2\varepsilon_1 R_0 \|\phi - \varphi\|,$$

and

$$\begin{split} & \|G(\cdot),\phi(\cdot),\phi_{\cdot}) - G(\cdot,\varphi(\cdot),\varphi_{\cdot})\| \\ & \leq \varepsilon_{2} \sup_{t\in\mathbb{T}} \left| (\phi_{2}(t)(\phi_{1}(t)+\varphi_{1}(t)),\varphi_{1}^{2}(t)) \begin{pmatrix} \phi_{1}(t)-\varphi_{1}(t)\\ \phi_{2}(t)-\varphi_{2}(t) \end{pmatrix} \right| \\ & \leq 2\varepsilon_{2}R_{0}^{2} \|\phi-\varphi\|. \end{split}$$

Hence, let  $L_Q = 2\varepsilon_1 R_0, L_G = \varepsilon_2 R_0^2, a = ||G(t, 0, 0)|| = \varepsilon_2$  and b = ||Q(t, 0)|| = 0. Thus, inequality (3.13) becomes

$$2\varepsilon_1 R_0^2 + k\varepsilon_2 (\frac{1}{\alpha} - \frac{1}{\ominus \alpha})(2R_0^3 + 1) \le R_0,$$

which is satisfied for small  $\varepsilon_1$  and  $\varepsilon_2$ . By Theorem 3.1, (4.1) has an almost periodic solution. Moreover,

$$2\varepsilon_1 R_0 + 2k\varepsilon_2 R_0^2 (\frac{1}{\alpha} - \frac{1}{\ominus \alpha}) < 1$$

is also satisfied for small  $\varepsilon_1$  and  $\varepsilon_2$ . By Theorem 3.2, (4.1) has a unique almost periodic solution.

#### References

- K. Gopalsamy, Stability and Oscillations in Population Dynamics, Kluwer Acad. Pub. Boston, 1992.
- [2] W. Xiong, J. Liang, Novel stability criteria for neutral systems with multiple time delays, Chaos, Solitons and Fractals, 32 (2007) 1735-1741.
- [3] A. Bellen, N. Guglielmi, A. Ruchli, Methods for linerar systems of circuit delay differential equations of neutral type, IEEE Trans. Circ. Syst-I, 46 (1999) 212-216.
- [4] A. Balanov, N. Janson, P. McClintock, R. Tucks, C. Wang, Bifurcation analysis of a neutral delay differential equation modelling the torsional motion of a driven drill-string, Chaos, Solitons and Fractals, 15 (2003) 381-394.
- [5] J. Zhou, T. Chen, L. Xiang, Robust synchronization of delayed neutral networks based on adaptive control and parameters identification, Chaos, Solitons and Fractals. 27 (2006) 905-913.
- [6] M. Islam, Y. Raffoul, Periodic solutions of neutral nonlinear system of differential equations with functional delay, J. Math. Anal. Appl., 331 (2007) 1175-1186.

- [7] S. Abbas, D. Bahuguna, Almost periodic solutions of neutral functional differential equations, Comput. Math. Appl., 55(11) (2008) 2593-2601.
- [8] Y. Raffoul, E. Yankson, Positive Periodic Solutions in Neutral Delay Difference Equations, Adv. Dyn. Sys. Appl., 5(1) (2010) 123-130.
- [9] M. Bohner, A. Peterson, Dynamic equations on time scales, An Introduction with Applications, Boston: Birkhauser, 2001.
- [10] S. Hilger, Analysis on measure chains-a unified approach to continuous and discrete calculus, Result. Math., 18 (1990) 18-56.
- [11] M. Hu, L. Wang, Dynamic inequalities on time scales with applications in permanence of predator-prey system, Discrete Dyn. Nat. Soc., Volume 2012, Article ID 281052.
- [12] M. Hu, L. Wang, Unique existence theorem of solution of almost periodic diffrential equations on time scales, Discrete Dyn. Nat. Soc., Volume 2012, Article ID 240735.
- [13] M. Hu, L. Wang, Positive periodic solutions for an impulsive neutral delay model of single-species population growth on time scales, WSEAS Trans. Math., 11(8) (2012) 705-715.
- [14] T. Li, Z. Han, S. Sun, Y. Zhao, Oscillation results for third order nonlinear delay dynamic equations on time scales, Bull. Malays. Math. Sci. Soc., (2)34(2) (2011) 639-648.
- [15] D. Chen, Bounded oscillation of second-order half-linear neutral delay dynamic equations, Bull. Malays. Math. Sci. Soc., (2), in press.
- [16] Y. Li, C. Wang, Almost periodic functions on time scales and applications, Discrete Dyn. Nat. Soc., Volume 2011, Article ID 727068.
- [17] Y. Li, C. Wang, Uniformly almost periodic functions and almost periodic solutions to dynamic equations on time scales, Abstr. Appl. Anal., Volume 2011, Article ID 341520.
- [18] D. Cheban, C. Mammana, Invariant manifolds, global attractors and almost periodic solutions of nonautonomous difference equations, Nonlinear Anal. TMA. 56 (4) (2004) 465-484.
- [19] C. He, Almost Periodic Differential Equations, Higher Education Publishing House, Beijing, 1992 (in Chinese).
- [20] D. Smart, Fixed points Theorem, Cambridge Univ. Press, Cambridge, UK, 1980.