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A Chain Regression Estimator in Two Phase Sampling Using Multi-auxiliary Information

B.K. PRADHAN

Department of Statistics, Utkal University, Bhubaneswar-751004, India bkpradhanuu@rediffmail.com

Abstract. In this paper the population mean of the study variable y is estimated in a two phase sampling setup using three auxiliary variables with chain regression concept when the population mean of one of the auxiliary variables is unknown and other auxiliary population mean are known.

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1. Introduction

Information on variables correlated with the main variable under study is popularly known as auxiliary information which may be fruitfully utilised either at planning stage or at design stage or at the information stage to arrive at improved estimator compared to those, not utilising auxiliary information. Use of auxiliary information for forming ratio and regression method of estimation were introduced during the 1930's with a comprehensive theory provided by Cochran [1]. Assuming knowledge of multi-auxiliary variables, multivariate ratio estimator was suggested by Olkin [5], multivariate difference estimator by Raj [7], multiple regression estimator by Shukla [11], weighted regression estimator by Srivastava [13, 14, 15] and Ratio-cumproduct estimator by Singh [12]. Extension of these estimators to different sampling designs were taken up by Tripathy [17, 18]. Further contribution are due to Rao and Mudholkar [8], Wright [19] and many others.

When information on any auxiliary variable x highly correlated with y is readily available on all units of the population, it is well known that ratio and regression estimators provide more efficient estimates of population mean of y, envisaging advance information on population mean \overline{X} of x. However, in certain practical situation when \overline{X} is unknown, information on auxiliary variables Z and W are readily available on all the units of the population, which may also be incorporated in the method of estimation.

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2. Two phase sampling set up

Consider a finite population U of size N indexed by quadruplet characters (y, x, z, w). Our purpose is to estimate the population mean \overline{Y} of a study variable y in the presence of three auxiliary variables x, z and w, when the population mean \overline{X} of x is unknown but information on z and w are available on all the units of the population.

Let us now consider a two phase sampling where in the first phase a large sample $S'(S' \subset U)$ of fixed size n' is drawn following SRSWOR and observe three auxiliary variables x, z and w to estimate \overline{X} , while in the second phase a sub-sample $S \subset S'$ of fixed size n is drawn by SRSWOR to observe the characteristic y under study.

3. Use of one auxiliary variable

The two phase regression estimators in this case will be

(3.1)
$$\overline{t}_{1(\operatorname{Reg})} = \overline{y}_n + b_{yx}(\overline{x}_{n'} - \overline{x}_n)$$

where b_{yx} is the sample regression coefficient of y on x calculated from data based on S and

$$\overline{x}_{n'} = \frac{1}{n'} \sum_{i \in S'} x_i \quad \overline{x}_n = \frac{1}{n} \sum_{i \in S} x_i \quad \text{and} \quad \overline{y}_n = \frac{1}{n} \sum_{i \in S} y_i.$$

The mean square error (MSE) of $\bar{t}_{1(\text{Reg})}$ by first order approximation is

(3.2)
$$MSE(\bar{t}_{1(\text{Reg})}) = \left(\frac{1}{n} - \frac{1}{N}\right)(1 - \rho_{yx}^2)S_y^2 + \left(\frac{1}{n'} - \frac{1}{N}\right)\rho_{yx}^2S_y^2$$

where

$$S_y^2 = \frac{1}{N-1} \sum_{i=1}^{N} (y_i - \overline{Y})^2$$

and ρ_{yx} is the correlation coefficient between y and x.

4. Use of second auxiliary variable

Swain [16], Kiregyera [2], Mukherjee *et al.* [4], Sahoo *et al.* [9] and Mishra *et al.* [3] used a second auxiliary variable z closely related to x to suggest different improved estimators assuming that the information on z is available on all the units of the population.

Kiregyera [2] has suggested a regression type estimator

(4.1)
$$\overline{t}_{2(\operatorname{Reg})}) = \overline{y}_n + b_{yx}[\overline{x}_{n'} + b_{xz}(\overline{Z} - \overline{z}_{n'}) - \overline{x}_n]$$

a technique earlier suggested by Swain [16] which yields

(4.2)
$$MSE(\bar{t}_{2(\text{Reg})}) = \left(\frac{1}{n} - \frac{1}{N}\right) (1 - \rho_{yx}^2) S_y^2 + (\rho_{yx}^2 + \rho_{yx}^2 \rho_{xz}^2 - 2\rho_{yx}\rho_{yz}\rho_{xz}) S_y^2.$$

Sahoo et al. [9] considered a chain regression type estimator

(4.3)
$$\overline{t}_{3(\operatorname{Re} g)} = \overline{y}_n + b_{yx}(\overline{x}_{n'} - \overline{x}_n) + b_{yz}(Z - \overline{z}_{n'}).$$

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The MSE of $\bar{t}_{3(\text{Reg})}$ to the first order of approximation is

(4.4)
$$MSE(\bar{t}_{3(\text{Reg})}) = \left(\frac{1}{n} - \frac{1}{N}\right)(1 - \rho_{yx}^2)S_y^2 + \left(\frac{1}{n'} - \frac{1}{N}\right)(\rho_{yx}^2 - \rho_{yz}^2)$$

Another regression type estimator suggested by Mukherjee et al. [4] is

(4.5)
$$\overline{t}_{4(\operatorname{Reg})} = \overline{y}_n + b_{yx.z} \left[\overline{x}_{n'} + b_{xz} (\overline{Z} - \overline{z}_{n'}) - \overline{x}_n \right] + b_{yz.x} (\overline{Z} - \overline{z}_n).$$

Using a generalized method, a regression type estimator suggested by Mishra and Rout [3] is

$$(4.6) \quad \overline{t}_{5(\operatorname{Reg})} = \overline{y}_n + b_{yx.z}(\overline{x}_{n'} - \overline{x}_n) + b_{yz.x}(\overline{Z} - \overline{z}_n) + (b_{yz} - b_{yz.x})(\overline{Z} - \overline{z}_{n'}).$$

In fact, on simplification $\overline{t}_{4(\text{Re g})} = \overline{t}_{5(\text{Re g})}$. It may be seen that (4.7)

$$MSE(\bar{t}_{4(\text{Reg})}) = MSE(\bar{t}_{5(\text{Reg})}) = \left(\frac{1}{n} - \frac{1}{N}\right)(1 - \rho_{y.xz}^2)S_y^2 + \left(\frac{1}{n'} - \frac{1}{N}\right)(1 - \rho_{yz}^2)S_y^2.$$

5. Suggested estimators

Since \overline{X} based on n' unit is an unbiased estimator of \overline{X} , a regression type estimator

(5.1)
$$\widehat{\overline{X}} = \overline{x}_{n'} + \beta_{xz.w}(\overline{Z} - \overline{z}_{n'}) + \beta_{xw.z}(\overline{W} - \overline{w}_{n'})$$

is found by considering the estimator

(5.2)
$$\overline{\overline{X}} = \lambda_1 \overline{x}_{n'} + \lambda_2 \overline{z}_1 + \lambda_3 \overline{Z} + \lambda_4 \overline{w}_{n'} + \lambda_5 \overline{W}$$

which is unbiased for \overline{X} by considering $\lambda_1 = 1$, $\lambda_2 = -\lambda_3$ and $\lambda_4 = -\lambda_5$ and then by minimizing the variance $\widehat{\overline{X}}$ given by

(5.3)
$$\overline{\overline{X}} = \overline{x}_{n'} + \lambda_2(\overline{z}_{n'} - \overline{Z}) + \lambda_4(\overline{w}_{n'} - \overline{W}).$$

Here

$$\overline{x}_{n'} = \frac{1}{n'} \sum_{i \in S'} x_i, \quad \overline{z}_{n'} = \frac{1}{n'} \sum_{i \in S'} z_i, \quad \overline{w}_{n'} = \frac{1}{n'} \sum_{i \in S'} w_i$$

and $\beta_{xz.w}$ and $\beta_{xw.z}$ are usual partial regression coefficients.

Let us consider a chain regression type estimator of \overline{Y} given by

(5.4)
$$\overline{t}^* = \overline{y}_n + \lambda_1^* (\overline{X} - \overline{x}_n) + \lambda_2^* (\overline{Z} - \overline{z}_n) + \lambda_3^* (\overline{W} - \overline{w}_n).$$

where $\overline{y}_n, \overline{x}_n, \overline{z}_n$ and \overline{w}_n are the sample mean based on *n* observations of the second phase and λ_1^*, λ_2^* and λ_3^* are suitable constants.

The optimum values of λ_1^* , λ_2^* and λ_3^* are obtained by minimising $V(\bar{t}^*)$ and we find

(5.5)
$$\lambda_1^* = \beta_{yx.zw}, \quad \lambda_2^* = \beta_{yz.xw} \text{ and } \lambda_3^* = \beta_{yw.xz}$$

where $\beta_{yx.zw}$, $\beta_{yz.xw}$ and $\beta_{yw.xz}$ are usual partial regression coefficients. When the partial regression coefficients are known, \overline{t}^* is an unbiased estimator of \overline{Y} with

(5.6)
$$V(\bar{t}^*) = \left(\frac{1}{n} - \frac{1}{N}\right) (1 - \rho_{y.xzw}^2) S_y^2 + \left(\frac{1}{n'} - \frac{1}{N}\right) (1 - \rho_{y.zw}^2) \rho_{yx.zw}^2 S_y^2$$

where $\rho_{y.xzw}$ and $\rho_{y.zw}$ are usual multiple correlation coefficients and $\rho_{yx.zw}$ is the usual partial correlation coefficient.

The estimators under consideration require advance knowledge of the population regression coefficients and partial regression coefficients, which are usually unknown. However, in practice the consistent estimators $b_{yx.zw}$, $b_{yz.xw}$ and $b_{yw.xz}$ of the population parameters $\beta_{yx.zw}$, $\beta_{yz.xw}$ and $\beta_{yw.xz}$ may be substituted for the purpose. Although the estimators will turn out to be biased, this bias would be negligible in large samples and the approximate mean square errors to O(1/n) will be equivalent to those derived and for large sample, the difference would be minimal.

6. Comparison of efficiency

Sahoo *et al.* [9] has established that $\bar{t}_{1(\text{Reg})}$ and $\bar{t}_{2(\text{Reg})}$ are less efficient than $\bar{t}_{3(\text{Reg})}$. Mishra and Rout [3] has proved that

(6.1)
$$MSE(\overline{t}_{5(\operatorname{Re} g)}) < MSE(\overline{t}_{3(\operatorname{Re} g)})$$

Now, from (4.7) and (5.6), we find

(6.2)
$$MSE(\overline{t}_{5(\operatorname{Reg})}) - V(\overline{t}^*) = \left[\left(\frac{1}{n} - \frac{1}{N} \right) A + \left(\frac{1}{n'} - \frac{1}{N} \right) B \right] S_y^2$$

where $A = \rho_{y.xzw}^2 - \rho_{y.xz}^2$ and $B = (1 - \rho_{yz}^2)\rho_{yx.z}^2 - (1 - \rho_{y.zw}^2)\rho_{yx.zw}^2$. On simplification, we find

(6.3)
$$A + B = (1 - \rho_{yz}^2) \rho_{yw.z}^2 \ge 0$$

Since

$$\left(\frac{1}{n} - \frac{1}{N}\right) > \left(\frac{1}{n'} - \frac{1}{N}\right),$$

we have from (6.3)

(6.4)
$$\left(\frac{1}{n} - \frac{1}{N}\right)A + \left(\frac{1}{n'} - \frac{1}{N}\right)B \ge \left(\frac{1}{n'} - \frac{1}{N}\right)(A+B) \ge 0.$$

Hence

(6.5)
$$MSE(\bar{t}_{5(\text{Reg})}) \ge V(\bar{t}^*)$$

The inequality (6.5) shows that \overline{t}^* is an improved regression estimator compared to $\overline{t}_{1(\text{Reg})}, \overline{t}_{2(\text{Reg})}, \overline{t}_{3(\text{Reg})}$ and $\overline{t}_{5(\text{Reg})}$.

7. Numerical illustration

Percent relative efficiency of different estimators compared to mean per unit estimator are presented in Table 2.

	Population I	Population II	
Source	"Spray congealing: Particle size	"Measurement of four characters	
	relationships using a centrifugal	of: Flucus Religiousament" by	
	wheel automizer" by Scott,	Pradhan, B.K. (2000)	
	Robinson, Pauls and Lantz		
	(1964)		
у	Mean surface-volume particle size	Length of petiole	
	of product		
х	Feed rate per unit whetted wheel	Length of pamina(blade) of the	
	periphery (gm/sec/cm)	leaf	
Z	Peripheral wheel veloc-	Width of the leaf at its widest	
	ity(cm/sec)	paint	
W	Feed Viscosity (poise)	Width of leaf half way along the	
		blade	
size	N=35	N=160	
ρ_{yx}	0.712296	0.5423	
ρ_{yz}	-0.8070192	0.6166	
$ ho_{yw}$	-0.1623959	0.2704	
ρ_{xz}	-0.2633457	0.8568	
ρ_{xw}	-0.0781118	0.7424	
ρ_{zw}	0.1335984	0.8027	

Table 1. Description of Population

Table 2. Relative efficiency of different estimators of population variance with respect to S_y^2 under comparison

Estimator	Auxiliary vari-	Percent Relative	Percent Relative
	ables used	Efficiency of Pop-	Efficiency of Pop-
		ulation I: $N = 35$,	ulation II: $N =$
		n' = 12, n = 8	160, $n' = 50, n =$
			20
\overline{y}_n	None	100	100
$\overline{t}_{1(\text{Reg})}$	X	128.08	125.26
$\overline{t}_{2(\text{Reg})}$	X, Z	159.03	145.75
$\overline{t}_{3(\text{Reg})}$	X, Z	243.36	147.31
$\overline{t}_{4(\operatorname{Reg})} = \overline{t}_{5(\operatorname{Reg})}$	X, Z	378.98	161.47
$\bar{t}^*_{(\text{Reg})}$	X, Z, W	436.27	204.28

Remark 7.1. $\overline{t}^*_{(\text{Reg})}$ has substantial gain in efficiency compared to $\overline{t}_{5(\text{Reg})}$, $\overline{t}_{4(\text{Reg})}$, $\overline{t}_{3(\text{Reg})}$, $\overline{t}_{2(\text{Reg})}$, $\overline{t}_{1(\text{Reg})}$, $\overline{t}_{1(\text{Reg})}$ and \overline{y}_n for the population under consideration.

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