# The Axiom of Hemi-Slant 3-Spheres in Almost Hermitian Geometry 

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#### Abstract

The axiom of hemi-slant 3-spheres is introduced. It is proved that if an almost Hermitian manifold $M$ with dimension $2 m \geq 6$ satisfies this axiom for some slant angle $\theta \in(0, \pi / 2)$, then $M$ has pointwise constant type $\alpha$ if and only if $M$ has pointwise constant anti-holomorphic sectional curvature $\alpha$, and using this result some conditions for constancy of sectional curvature of a considered almost Hermitian manifold are given.


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## 1. Introduction

In [2], Cartan defined the axiom of n-planes. A Riemannian manifold $M$ of dimension $m \geq 3$ is said to satisfy the axiom of $n$-planes, where $n$ is a fixed integer $2 \leq n \leq m-1$, if for each point $p \in M$ and any $n$-dimensional subspace $\sigma$ of the tangent space $T_{p} M$ there exists an $n$-dimensional totally geodesic submanifold $N$ such that $p \in N$ and $T_{p} N=\sigma$. He gave a criterion for constancy of sectional curvature in the following theorem.

Theorem 1.1. Let $M$ be a Riemannian manifold of dimension $m \geq 3$. If $M$ satisfies the axiom of $n$-planes for some $n, 2 \leq n \leq m-1$, then $M$ has constant sectional curvature.

In [21], Yano and Mogi applied Cartan's idea to Kaehlerian manifolds. A Kaehlerian manifold $M$ is said to satisfy the axiom of holomorphic planes if for each point $p \in M$ and each holomorphic plane $\sigma \subset T_{p} M$, there exists a totally geodesic submanifold $N$ such that $p \in N$ and $T_{p} N=\sigma$. They proved the following theorem.

Theorem 1.2. A Kaehlerian manifold satisfying the axiom of holomorphic planes is a complex space form.

In [12], Leung and Nomizu defined the axiom of $n$-spheres by taking totally umbilical submanifold $N$ with parallel mean curvature vector field instead of totally geodesic submanifold $N$ in the axiom of $n$-planes. They proved the following theorem.

[^0]Theorem 1.3. If a Riemannian manifold $M$ of dimension $m \geq 3$ satisfies the axiom of $n$ spheres for some $n, 2 \leq n \leq m-1$, then $M$ has constant sectional curvature.

Afterwards, many studies have been made in this direction. Kaehlerian manifolds were studied in [4, 6, 8, 11, 19], the papers [17] and [19] discussed nearly Kaehlerian (almost Tachibana) manifolds, and results concerning larger classes of almost Hermitian manifolds can be found in $[9,10,16,17]$.

In this paper, we shall introduce the axiom of hemi-slant 3 -spheres and as an application, we shall give an interesting relation between the notion of constant type and antiholomorphic sectional curvature for a $2 m(m \geq 3)$-dimensional almost Hermitian manifold satisfying this axiom for some slant angle $\theta \in(0, \pi / 2)$. Using this fact, we shall prove some theorems related to sectional curvature for a considered almost Hermitian manifold. We shall also give some results related to the Weyl conformal curvature tensor and the Bochner curvature tensor of a certain almost Hermitian manifold satisfying the axiom of hemi-slant 3 -spheres. Our work is motivated by the above-cited papers.

## 2. Preliminaries

A $C^{\infty}$-manifold $M$ is called almost Hermitian if its tangent bundle has an almost complex structure $J$ and a Riemannian metric $g$ such that $g(J X, J Y)=g(X, Y)$ for all $X, Y \in \chi(M)$, where $\chi(M)$ is the Lie algebra of $C^{\infty}$ vector fields on $M$. Let $\nabla$ be the covariant derivative on $M$, the Riemannian curvature tensor $R$ associated with $\nabla$ defined by $R(X, Y)=$ $\nabla_{[X, Y]}-\left[\nabla_{X}, \nabla_{Y}\right]$. We denote $g(R(X, Y) Z, U)$ by $R(X, Y, Z, U)$. The sectional curvature $K$ of $M$ determined by orthonormal vector fields $X$ and $Y$ is given by $K(X, Y)=R(X, Y, X, Y)$. The Weyl conformal curvature tensor $W$ is defined by

$$
\begin{aligned}
W & (X, Y, Z, U) \\
= & R(X, Y, Z, U)-\frac{1}{2 m-2}\{g(X, U) \operatorname{Ric}(Y, Z)-g(X, Z) \operatorname{Ric}(Y, U)+g(Y, Z) \operatorname{Ric}(X, U) \\
& -g(Y, U) \operatorname{Ric}(X, Z)\}+\frac{S}{(2 m-1)(2 m-2)}\{g(X, U) g(Y, Z)-g(X, Z) g(Y, U)\}
\end{aligned}
$$

for all $X, Y, Z, U \in T_{p} M$, where Ric and $S$ are the Ricci tensor and the scalar curvature of $M$, respectively. A $2 m$-dimensional almost Hermitian manifold with $m \geq 2$ is conformally flat if and only if $W=0$ identically [10,20].

By an $r$-plane we mean an $r$-dimensional linear subspace of a tangent space $T_{p} M, p \in M$. Motivated from [3], we have the following definition.
Definition 2.1. Let $\sigma$ be a 2-plane. The angle $\theta \in[0, \pi / 2]$ between $\sigma$ and $J \sigma$ is defined by

$$
\cos \theta=|g(X, J Y)|
$$

where $\{X, Y\}$ is an orthonormal basis of $\sigma$. If $\theta=$ constant, then $\sigma$ is called a slant-plane and $\theta$ is called slant angle of $\sigma$.

This is a generalization of holomorphic and anti-holomorphic planes. In fact, holomorphic and anti-holomorphic planes are slant planes with slant angle $\theta$ equal to 0 and $\pi / 2$, respectively, see [4,6,8]. Now, motivated from [1] and [14] we have the following definition.
Definition 2.2. A 3-plane $\sigma$ in $T_{p} M$ is called hemi-slant if it contains a slant 2-plane with slant angle $\theta \in[0, \pi / 2)$ and a nonzero vector $Z \in T_{p} M$ such that $J Z$ is perpendicular to $\sigma$, in which case $\sigma=D^{\theta} \oplus\{Z\}$ with $J Z \perp \sigma$, where $D^{\theta}$ is the corresponding slant 2-plane.

The sectional curvature of $M$ restricted to a holomorphic (resp. an anti-holomorphic) plane $\sigma$ is called holomorphic (resp. anti-holomorphic) sectional curvature. If the holomorphic (resp. anti-holomorphic) sectional curvature at each point $p \in M$, does not depend on $\sigma$, then $M$ is said to be pointwise constant holomorphic (resp. pointwise constant antiholomorphic) sectional curvature. A connected Riemannian (resp. Kaehlerian) manifold of (global) constant sectional curvature (resp. of constant holomorphic sectional curvature) is called a real space form (resp. a complex space form) [9,20]. The following useful notion was defined by Gray in [7].

Definition 2.3. Let $M$ be an almost Hermitian manifold. Then $M$ is said to be of constant type at $p \in M$ provided that for all $X \in T_{p} M$, we have $\lambda(X, Y)=\lambda(X, Z)$ whenever the planes span $\{X, Y\}$ and $\operatorname{span}\{X, Z\}$ are anti-holomorphic and $g(Y, Y)=g(Z, Z)$, where the function $\lambda$ is defined by $\lambda(X, Y)=R(X, Y, X, Y)-R(X, Y, J X, J Y)$. If this holds for all $p \in M$, then we say that $M$ has (pointwise) constant type. Finally, if for $X, Y \in \chi(M)$ with $g(X, Y)=g(J X, Y)=0$, the value $\lambda(X, Y)$ is constant whenever $g(X, X)=g(Y, Y)=1$, then we say that $M$ has global constant type.

Vanhecke introduced to the notion of $R K$-manifold in [16]. An almost Hermitian manifold $M$ is called an $R K$-manifold if

$$
\begin{equation*}
R(X, Y, Z, U)=R(J X, J Y, J Z, J U) \tag{2.1}
\end{equation*}
$$

for all $X, Y, Z, U \in \chi(M)$. He proved many theorems. Recall some of them.
Theorem 2.1. [16] Let $M$ be an $R K$-manifold. Then $M$ has (pointwise) constant type if and only if there exists $\alpha \in \mathscr{F}(M)$ such that

$$
\lambda(X, Y)=\alpha\left\{g(X, X) g(Y, Y)-g^{2}(X, Y)-g^{2}(X, J Y)\right\},
$$

for all $X, Y \in \chi(M)$. Furthermore, $M$ has global constant type if and only if $\alpha$ is a constant function.

Theorem 2.2. [16] Let $M$ be an $R K$-manifold. Suppose that $M$ has constant holomorphic sectional curvature $\mu$ at a point $p \in M$, let $X, Y \in T_{p} M$ be any orthonormal vectors. Then we have

$$
K(X, Y)=\frac{\mu}{4}\left\{1+3 g^{2}(X, J Y)\right\}+\frac{5}{8} \lambda(X, Y)+\frac{1}{8} \lambda(X, J Y),
$$

where $K(X, Y)$ is sectional curvature determined by $X$ and $Y$.
Theorem 2.3. [16] Let $M$ be an RK-manifold with pointwise constant anti-holomorphic (resp. holomorphic) sectional curvature $v$ (resp. $\mu$ ). Then $M$ has pointwise constant holomorphic (resp.anti-holomorphic) sectional curvature $\mu$ (resp. v) if and only if $M$ has pointwise constant type $\alpha$, in which case

$$
4 v=\mu+3 \alpha
$$

The dimension of $M$ is supposed to be $\geq 6$.
We shall call an almost Hermitian manifold $M$ as Kaehlerian if $\nabla_{X} J=0$ for all $X \in$ $\chi(M)$, nearly Kaehlerian (almost Tachibana or $K$-space) if $\left(\nabla_{X} J\right) X=0$ for all $X \in \chi(M)$, and para-Kaehlerian if $R(X, Y, Z, U)=R(X, Y, J Z, J U)$ for all $X, Y, Z, U \in \chi(M)$. These manifolds satisfy (2.1), so they are $R K$-manifolds. It is easy to see that a para-Kaehlerian manifold has global constant type [16, 17].

For a $2 m$-dimensional Kaehlerian manifold, the Bochner curvature tensor $B$ is defined by

$$
\begin{aligned}
& B(X, Y, Z, U) \\
&= R(X, Y, Z, U)-\frac{1}{2(m+2)}\{g(X, U) \operatorname{Ric}(Y, Z)-g(X, Z) \operatorname{Ric}(Y, U)+g(Y, Z) \operatorname{Ric}(X, U) \\
&-g(Y, U) \operatorname{Ric}(X, Z)+g(X, J U) \operatorname{Ric}(Y, J Z)-g(X, J Z) \operatorname{Ric}(Y, J U)+g(Y, J Z) \operatorname{Ric}(X, J U) \\
&-g(Y, J U) \operatorname{Ric}(X, J Z)-2 g(X, J Y) \operatorname{Ric}(Z, J U)-2 g(Z, J U) \operatorname{Ric}(X, J Y)\} \\
&+\frac{S}{4(m+1)(m+2)}\{g(X, U) g(Y, Z)-g(X, Z) g(Y, U)\} \\
&+g(X, J U) g(Y, J Z)-g(X, J Z) g(Y, J U)-2 g(X, J Y) g(Z, J U)
\end{aligned}
$$

for all $X, Y, Z, U \in T_{p} M$ and $p \in M$, where Ric and $S$ are the Ricci tensor and the scalar curvature of $M$, respectively [11]. The following lemma gives a criterion for vanishing of the Bochner curvature tensor of a Kaehlerian manifold.

Lemma 2.1. [11] A Kaehlerian manifold $M$ of dimension $2 m \geq 6$ has a vanishing Bochner curvature tensor, if and only if for each point $p \in M$ and for all unit vectors $X, Y, Z \in T_{p} M$, which span an anti-holomorphic 3-plane

$$
R(X, J X, Y, Z)=2 R(X, Y, J X, Z)
$$

holds.
Now, we give some definitions related to submanifolds.
Let $M$ be a $C^{\infty}$-Riemannian manifold with metric tensor $g$ and $N$ be a submanifold of $M$. We denote by $\nabla$ and $\hat{\nabla}$ the covariant derivatives on $M$ and $N$ respectively. For any vector fields $X$ and $Y$ tangent to $N$, the second fundamental form $T$ is defined by

$$
T(X, Y)=\nabla_{X} Y-\hat{\nabla}_{X} Y
$$

where $\hat{\nabla}_{X} Y$ is tangent to $N$ and $T(X, Y)$ is normal to $N$. The normal bundle-valued form $T$ is a symmetric tensor field of type $(0,2)$. We say that $N$ is totally umbilical submanifold in $M$ if for all $X, Y$ tangent to $N$, we have

$$
\begin{equation*}
T(X, Y)=g(X, Y) \eta \tag{2.2}
\end{equation*}
$$

where $\eta$ is the mean curvature vector field of $N$ in $M$. The Codazzi equation is given by

$$
\begin{equation*}
(R(X, Y) Z)^{\perp}=\left(\nabla_{X} T\right)(Y, Z)-\left(\nabla_{Y} T\right)(X, Z) \tag{2.3}
\end{equation*}
$$

for all $X, Y, Z$ tangent to $N$. Where ${ }^{\perp}$ denotes the normal component and the covariant derivative of $T$, denoted by $\nabla_{X} T$, is defined by

$$
\begin{equation*}
\left(\nabla_{X} T\right)(Y, Z)=D_{X}(T(Y, Z))-T\left(\hat{\nabla}_{X} Y, Z\right)-T\left(Y, \hat{\nabla}_{X} Z\right) \tag{2.4}
\end{equation*}
$$

for all $X, Y, Z$ tangent to $N$, where $D$ denotes the operator of covariant derivative in the normal bundle of $N[4,6,8,19]$.

## 3. Main results

We now introduce the following axiom.

Definition 3.1. (Axiom of hemi-slant 3-spheres). An almost Hermitian manifold $M$ is said to satisfy the axiom of hemi-slant 3-spheres if for each point $p \in M$ and each hemi-slant 3-plane $\sigma$ in $T_{p} M$, there exists a 3-dimensional totally umbilical submanifold $N$ such that $p \in N$ and $T_{p} N=\sigma$.

Before studying the axiom of hemi-slant 3-spheres, let us note the following.
Remark 3.1. Let $M$ be any $2 m$-dimensional almost Hermitian manifold with $m \geq 3$ and let $\left\{X_{1}, \ldots, X_{m}, J X_{1}, \ldots, J X_{m}\right\}$ be an orthonormal $J$-basis of $T_{p} M$. Then we always have a hemislant 3-plane with the slant angle $\theta$. For example, $\sigma=D^{\theta} \oplus\left\{X_{3}\right\}$ is a hemi-slant 3-plane with the slant angle $\theta$, where $D^{\theta}=\operatorname{span}\left\{X_{1}, \cos \theta J X_{1}+\sin \theta X_{2}\right\}$.

Lemma 3.1. Let $M$ be an almost Hermitian manifold with dimension $2 m \geq 6$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then we have

$$
\begin{equation*}
\lambda(X, Y)=K(X, Y) \tag{3.1}
\end{equation*}
$$

for all orthonormal vectors $X, Y \in T_{p} M$ with $g(X, J Y)=0$, where $\lambda(X, Y)=R(X, Y, X, Y)-$ $R(X, Y, J X, J Y)$ and $K$ denotes anti-holomorphic sectional curvature.

Proof. Let $p$ be an arbitrary point of $M$ and let $X, Y$ and $Z$ be any orthonormal vectors in $T_{p} M$ with $g(X, J Y)=g(X, J Z)=g(Y, J Z)=0$. Consider the hemi-slant 3-plane $\sigma=D^{\theta} \oplus\{Y\}$ with slant angle $\theta \in(0, \pi / 2)$, where $D^{\theta}=\operatorname{span}\{X, \cos \theta J X+\sin \theta Z\}$. By the axiom of hemi-slant 3 -spheres, there exists a 3 -dimensional totally umbilical submanifold $N$ such that $p \in N$ and $T_{p} N=\sigma$. Then, with the help of (2.2) and (2.4) from (2.3), we have

$$
\begin{equation*}
(R(X, Y)(\cos \theta J X+\sin \theta Z))^{\perp}=0 \tag{3.2}
\end{equation*}
$$

Since $J Y$ is normal to $N$, we get

$$
\begin{equation*}
R(X, Y, \cos \theta J X+\sin \theta Z, J Y)=0 \tag{3.3}
\end{equation*}
$$

Now, consider the hemi-slant 3-plane $\sigma_{2}=D_{2}^{\theta} \oplus\{Y\}$ with slant angle $\theta \in(0, \pi / 2)$, where $D_{2}^{\theta}=\operatorname{span}\{X, \cos \theta J X-\sin \theta Z\}$. By a similar method, we can obtain

$$
\begin{equation*}
R(X, Y, \cos \theta J X-\sin \theta Z, J Y)=0 \tag{3.4}
\end{equation*}
$$

From (3.3) and (3.4) we get

$$
\begin{equation*}
R(X, Y, J X, J Y)=0 \tag{3.5}
\end{equation*}
$$

From Definition 2.3, and the equation (3.5), we obtain (3.1).
Theorem 3.1. Let $M$ be an almost Hermitian manifold with dimension $2 m \geq 6$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then $M$ has pointwise constant type if and only if $M$ has pointwise constant anti-holomorphic sectional curvature.

Proof. Let $M$ be an almost Hermitian manifold with dimension $2 m \geq 6$ satisfying the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$. If $M$ has pointwise constant type; that is, for all $p \in M, M$ has constant type at $p$, then for all $X, Y, Z \in T_{p} M$, we have

$$
\begin{equation*}
\lambda(X, Y)=\lambda(X, Z) \tag{3.6}
\end{equation*}
$$

whenever the planes span $\{X, Y\}$ and $\operatorname{span}\{X, Z\}$ are anti-holomorphic and $g(Y, Y)=g(Z, Z)$. Here, we can assume that $g(Y, Y)=g(Z, Z)=1$. Thus, from Lemma 3.1, we get

$$
\begin{equation*}
K(X, Y)=K(X, Z) \tag{3.7}
\end{equation*}
$$

for all orthonormal vectors $X, Y, Z \in T_{p} M$ with $g(X, J Y)=g(X, J Z)=0$.
On the other hand, since the dimension of $M$ is greater than 6 we can choose a unit vector $U$ in $(\operatorname{span}\{X, J X\})^{\perp} \cap(\operatorname{span}\{Z, J Z\})^{\perp}$. Then, from (3.7), we have

$$
\begin{equation*}
K(X, U)=K(X, Z) \tag{3.8}
\end{equation*}
$$

This implies that the sectional curvature is the same for all anti-holomorphic sections which contain any given vector $X$. Hence we write

$$
\begin{equation*}
K(X, Y)=K(Y, Z)=K(Z, U) \tag{3.9}
\end{equation*}
$$

Therefore, we find

$$
\begin{equation*}
K(X, Y)=K(Z, U) \tag{3.10}
\end{equation*}
$$

for all $X, Y, Z, U \in T_{p} M$ whenever the planes $\operatorname{span}\{X, Y\}$ and $\operatorname{span}\{Z, U\}$ are anti-holomorphic. It follows that the sectional curvature is the same for all anti-holomorphic sections at $p \in M$; that is, $M$ has pointwise constant anti-holomorphic sectional curvature.

Conversely, let $M$ be of pointwise constant anti-holomorphic sectional curvature and let $p$ be any point of $M$. Then for all orthonormal vectors $X, Y, Z \in T_{p} M$ with $g(X, J Y)=$ $g(X, J Z)=0,(\operatorname{span}\{X, Y\}$ and $\operatorname{span}\{X, Z\}$ are anti-holomorphic planes and $g(X, X)=g(Y$, $Y)=g(Z, Z)=1)$, we have

$$
\begin{equation*}
K(X, Y)=K(X, Z) \tag{3.11}
\end{equation*}
$$

From Lemma 3.1, we get

$$
\begin{equation*}
\lambda(X, Y)=\lambda(X, Z) \tag{3.12}
\end{equation*}
$$

for all orthonormal vectors $X, Y, Z \in T_{p} M$ whenever the planes span $\{X, Y\}$ and $\operatorname{span}\{X, Z\}$ are anti-holomorphic. It is not difficult to see that (3.12) also holds in the case $g(Y, Y)=$ $g(Z, Z) \neq 1$. It follows that $M$ has constant type at $p$.

With the help of Lemma 3.1, from Theorem 3.1, we have the following result.
Corollary 3.1. Let $M$ be a $2 m$-dimensional almost Hermitian manifold with $m \geq 3$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then $M$ has pointwise constant type $\alpha$ if and only if $M$ has pointwise constant anti-holomorphic sectional curvature $\alpha$.

We now state the main result of the present work.
Theorem 3.2. Let $M$ be a $2 m$-dimensional (connected) $R K$-manifold with pointwise constant type $\alpha$ and $m \geq 3$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in$ $(0, \pi / 2)$, then $M$ is a real space form with constant sectional curvature $\alpha$ and $M$ has global constant type.

Proof. Let $p$ be any point of $M$ and $M$ has constant type $\alpha$ at $p$. Then it follows from Corollary 3.1 that $M$ has constant anti-holomorphic sectional curvature $\alpha$ at $p$. On the other hand, from Theorem 2.3, we see that $M$ has constant holomorphic sectional curvature $\alpha$ at $p$. With the help of Theorem 2.1, from Theorem 2.2, we obtain

$$
\begin{equation*}
K(X, Y)=\alpha \tag{3.13}
\end{equation*}
$$

for all orthonormal vectors $X, Y \in T_{p}(M)$, where $K(X, Y)=R(X, Y, X, Y)$ is sectional curvature. It is not difficult to see that (3.13) is also true for all $X, Y \in T_{p}(M)$. By the well-known

Schur's theorem [20] it follows that $M$ has constant sectional curvature $\alpha$ and $M$ has global constant type.

Corollary 3.2. Let $M$ be a $2 m$-dimensional (connected) $R K$-manifold with vanishing constant type and $m \geq 3$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then $M$ is flat.

Now, suppose that $M$ is a Kaehlerian manifold. Then, for all $X, Y, Z \in \chi(M)$, as a result of the Kaehler identity $R(X, Y) J Z=J R(X, Y) Z$, we get $R(J X, J Y) Z=R(X, Y) Z$ [20]. In this case, we have

$$
\begin{equation*}
R(J X, J Y, J X, J Y)=R(X, Y, J X, J Y) \tag{3.14}
\end{equation*}
$$

Using (2.1) and (3.14), we can see that $\lambda(X, Y)=0$. Thus, any Kaehlerian manifold has (global) vanishing constant type. Thus, it follows from Corollary 3.2 that:

Corollary 3.3. Let $M$ be a $2 m$-dimensional (connected) Kaehlerian or para-Kaehlerian manifold with $m \geq 3$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then $M$ is flat.

Theorem 3.3. Let $M$ be a $2 m$-dimensional (connected) non-Kaehlerian nearly Kaehlerian manifold with constant type $\alpha$ and $m \geq 3$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then $M$ has constant sectional curvature $\alpha>0$ and $m=3$.
Proof. In [7], for a nearly Kaehlerian manifold $M$, A. Gray proved the following.

$$
\begin{equation*}
\lambda(X, Y)=R(X, Y, X, Y)-R(X, Y, J X, J Y)=\left\|\left(\nabla_{X} J\right) Y\right\|^{2}, \tag{3.15}
\end{equation*}
$$

where $X, Y \in \chi(M)$. Now, let $M$ be a $2 m$-dimensional non-Kaehlerian nearly Kaehlerian manifold with constant type $\alpha$ and $m \geq 3$. Then, it follows from (3.15) that $\alpha=\lambda(X, Y)=$ $\left\|\left(\nabla_{X} J\right) Y\right\|^{2}>0$ due to $M$ is non-Kaehlerian. On the other hand, since $M$ satisfies the axiom of hemi-slant 3-spheres for some $\theta \in(0, \pi / 2)$, by Theorem 3.2, we have $M$ has constant sectional curvature $\alpha$. Hence, we see that $M$ has constant holomorphic sectional curvature $\alpha$. Thus, the assertion $m=3$ follows from the following theorem.

Theorem 3.4. [15] Except for the 6-dimensional one, there does not exist a non-Kaehlerian nearly Kaehlerian manifold of constant holomorphic sectional curvature.

Now, we give a result related to the Weyl conformal curvature tensor.
Theorem 3.5. Let $M$ be an almost Hermitian manifold with dimension $2 m \geq 8$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then $M$ is conformally flat.
Proof. Let $p$ be an arbitrary point of $M$ and let $X, Y$ and $Z$ be any orthonormal vectors of $T_{p} M$ with $g(X, J Y)=g(X, J Z)=g(Y, J Z)=0$. Consider the hemi-slant 3-plane $\sigma_{1}=D_{1}^{\theta} \oplus$ $\{Z\}$ with slant angle $\theta \in(0, \pi / 2)$, where $D_{1}^{\theta}=\operatorname{span}\{X, \cos \theta J X+\sin \theta Y\}$ and the hemislant 3-plane $\sigma_{2}=D_{2}^{\theta} \oplus\{Z\}$ with slant angle $\theta \in(0, \pi / 2)$, where $D_{2}^{\theta}=\operatorname{span}\{X, \cos \theta J X-$ $\sin \theta Y\}$. As in the proof of Lemma 3.1, by the axiom of hemi-slant 3 -spheres and by the equation (2.3), we have

$$
\begin{equation*}
(R(X, \cos \theta J X+\sin \theta Y) Z)^{\perp}=0 \tag{3.16}
\end{equation*}
$$

and

$$
\begin{equation*}
(R(X, \cos \theta J X-\sin \theta Y) Z)^{\perp}=0 \tag{3.17}
\end{equation*}
$$

On the other hand, since the dimension of $M$ is greater than 8 we can choose a unit vector $U$ in $(\operatorname{span}\{X, J X\})^{\perp} \cap(\operatorname{span}\{Y, J Y\})^{\perp} \cap(\operatorname{span}\{Z, J Z\})^{\perp}$. Thus, we write

$$
\begin{equation*}
R(X, \cos \theta J X+\sin \theta Y, Z, U)=0 \tag{3.18}
\end{equation*}
$$

and

$$
\begin{equation*}
R(X, \cos \theta J X-\sin \theta Y, Z, U)=0 \tag{3.19}
\end{equation*}
$$

From (3.18) and (3.19), we have

$$
\begin{equation*}
R(X, J X, Z, U)=0 . \tag{3.20}
\end{equation*}
$$

On the other hand, (3.18) and (3.20) give

$$
\begin{equation*}
R(X, Y, Z, U)=0 \tag{3.21}
\end{equation*}
$$

where $X, Y, Z, U \in T_{p} M$ span an anti-holomorphic 4-plane. According to a well-known theorem of Schouten [13], the Weyl conformal curvature tensor $W$ of $M$ vanishes. This completes the proof.

Next, we will give a result related to the Bochner curvature tensor.
Theorem 3.6. Let $M$ be a Kaehlerian manifold with dimension $2 m \geq 6$. If $M$ satisfies the axiom of hemi-slant 3 -spheres for some $\theta \in(0, \pi / 2)$, then $M$ has a vanishing Bochner curvature tensor.

Proof. Let $p$ be any point of $M$ and let $X, Y$ and $Z$ be any orthonormal vectors of $T_{p} M$ with $g(X, J Y)=g(X, J Z)=g(Y, J Z)=0$; that is, they span an anti-holomorhic 3-plane. Then the 3-plane $\sigma_{1}=D_{1}^{\theta} \oplus\{Y\}$ is a hemi-slant 3-plane with slant angle $\theta \in(0, \pi / 2)$, where $D_{1}^{\theta}=\operatorname{span}\{X, \cos \theta J X+\sin \theta J Z\}$. By the axiom of hemi-slant 3-spheres, there exists a 3dimensional totally umbilical submanifold $N_{1}$ such that $p \in N_{1}$ and $T_{p} N_{1}=\sigma_{1}$. Then, with the help of (2.2) and (2.4) from (2.3), we have

$$
\begin{equation*}
(R(X, \cos \theta J X+\sin \theta J Z) Y)^{\perp}=0 \tag{3.22}
\end{equation*}
$$

and

$$
\begin{equation*}
(R(X, Y)(\cos \theta J X+\sin \theta J Z))^{\perp}=0 \tag{3.23}
\end{equation*}
$$

Since $Z$ is normal to $N_{1}$, from (3.22) and (3.23) we get

$$
\begin{equation*}
R(X, \cos \theta J X+\sin \theta J Z, Y, Z)=0 \tag{3.24}
\end{equation*}
$$

and

$$
\begin{equation*}
R(X, Y, \cos \theta J X+\sin \theta J Z, Z)=0 \tag{3.25}
\end{equation*}
$$

Now, consider the hemi-slant 3-plane $\sigma_{2}=D_{2}^{\theta} \oplus\{Y\}$ with slant angle $\theta \in(0, \pi / 2)$, where $D_{2}^{\theta}=\operatorname{span}\{X, \cos \theta J X-\sin \theta J Z\}$. Again by the axiom of hemi-slant 3-spheres, there exists a 3-dimensional totally umbilical submanifold $N_{2}$ such that $p \in N_{2}$ and $T_{p} N_{2}=\sigma_{2}$. Then, with the help of (2.2) and (2.4) from (2.3), we have

$$
\begin{equation*}
(R(X, \cos \theta J X-\sin \theta J Z) Y)^{\perp}=0 \tag{3.26}
\end{equation*}
$$

and

$$
\begin{equation*}
(R(X, Y)(\cos \theta J X-\sin \theta J Z))^{\perp}=0 \tag{3.27}
\end{equation*}
$$

Since $Z$ is normal to $N_{2}$, from (3.26) and (3.27) we get

$$
\begin{equation*}
R(X, \cos \theta J X-\sin \theta J Z, Y, Z)=0 \tag{3.28}
\end{equation*}
$$

and

$$
\begin{equation*}
R(X, Y, \cos \theta J X-\sin \theta J Z, Z)=0 \tag{3.29}
\end{equation*}
$$

From (3.24) and (3.28) we obtain

$$
\begin{equation*}
R(X, J X, Y, Z)=0 \tag{3.30}
\end{equation*}
$$

On the other hand, from (3.25) and (3.29) we obtain

$$
\begin{equation*}
R(X, Y, J X, Z)=0 \tag{3.31}
\end{equation*}
$$

Thus, our assertion follows from (3.30), (3.31) and Lemma 2.1.
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